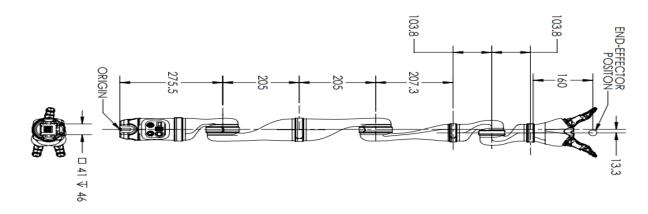


# JACO<sup>2</sup> Spherical 7 DOF Technical specifications





# JACO<sup>2</sup> Spherical 7 DOF





# **GENERAL**

TOTAL WEIGHT 4,4 Kg

MATERIALS Carbon fiber (links), Aluminum (actuators)

PAYLOAD 2.4 Kg (mid-range continuous payload capabilities)

2.1 Kg (full-reach peak/temporary payload capabilities)

REACH 98.5 cm

JOINT RANGE AFTER START-UP (SOFTWARE

LIMITATION)

±27.7 turns

MAXIMUM LINEAR ARM SPEED 20 cm/s

POWER SUPPLY VOLTAGE 18 to 29 VDC

AVERAGE POWER 25 W (5W in STANDBY)

PEAK POWER 100 W

COMMUNICATION PROTOCOL RS485

COMMUNICATION CABLES 20 pins flat flex cable

2 EXPANSION PINS ON COMMUNICATION BUS

WATER RESISTANCE IPX2

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**OPERATING TEMPERATURE** 

-10 °C to 40 °C expected

### **CONTROLLER**

**PORTS** 

Joystick1 Mbps CANBUSPower supply18 to 29 VDCUSB 2.0 (API)12 MbpsEthernet100 Mbps

CONTROL SYSTEM FREQUENCY 100 Hz (High Level API)

500 Hz (Low Level API)

CPU 360 MHz

SDK

APIs High and low level

Compatibility Windows, Linux Ubuntu & ROS

Port USB 2.0 Programming languages C++

FORCE, CARTESIAN & ANGULAR CONTROL

## **DETAILED SPECIFICATIONS**

ACTUATORS #1, #2, #3, #4 K-75+

ACTUATORS #5, #6 & #7 K-58



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